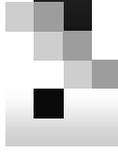


IPC-4

Stefan Edelkamp, University of Dortmund

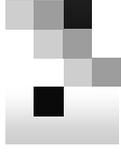
(joint work with

Jörg Hoffmann University of Freiburg)



Overview

- IPC History
- PDDL
- Evaluation
- Benchmarks
- Organisation
- Summary



Overview

- ***IPC History***
- PDDL
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IPC-1, IPC-2, and IPC-3

- **AIPS-98 McDermott** PDDL (STRIPS & ADL);
5 competitors: IPP, HSP, STAN, Blackbox, SGP; no clear-cut winner
- **AIPS-00 Bacchus**; automated vs. hand-coded,
16 competitors, awards: FF/TALplanner, STAN, System R, MIPS, HSP-2 / Shop
- **AIPS-02 Fox & Long**; PDDL2.1 (numbers, duration and optimization metrics),
15 competitors, awards: LPG / TLplan, MIPS / Shop2, VHPOP



IPC-4

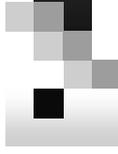
- **Co-Chairs**

Edelkamp & Hoffmann: Classical Planning

Littman & Younes: Probabilistic Planning

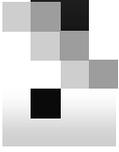
- **Committee**

*Maria Fox, Derek Long, Fahiem Bacchus,
Drew McDermott, David Smith, Daniel Weld,
Alessandro Cimatti, Jussi Rintanen, Enrico
Giunchiglia, Blai Bonet*



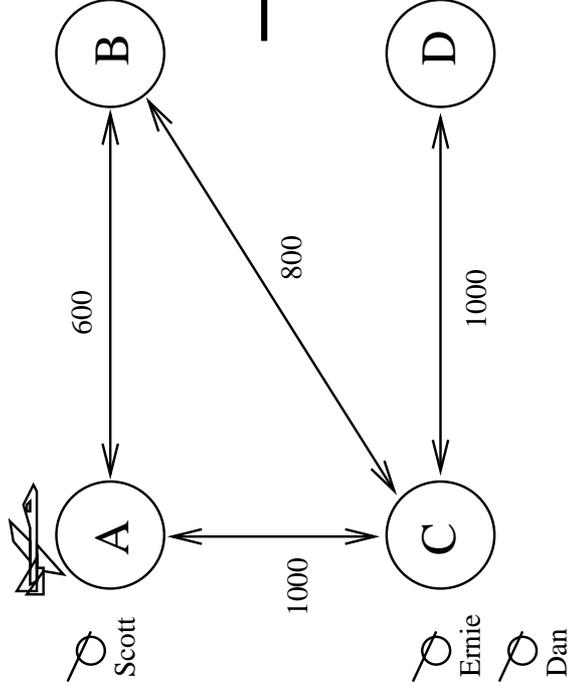
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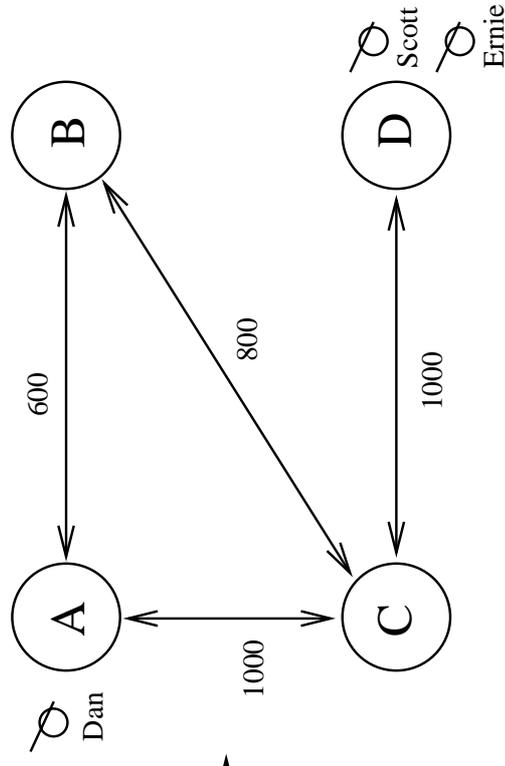


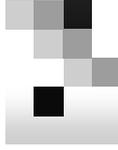
Example

Startzustand



Zielzustand





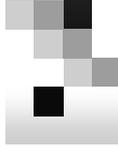
Domain Description

Predicates & Functions

```
(define (domain zeno-travel)
  (:predicates
    (at ?x - aircraft ?c - city)
    (in ?p - person ?a - aircraft))
  (:functions (fuel ?a - aircraft)
    (distance ?c1 - city ?c2 - city)
    (slow-speed ?a - aircraft)
    (fast-speed ?a - aircraft)
    (slow-burn ?a - aircraft)
    (fast-burn ?a - aircraft)
    (capacity ?a - aircraft)
    (refuel-rate ?a - aircraft)
    (total-fuel-used)
    (boarding-time)
    (debarking-time)))
```

Actions

```
(:durative-action zoom
  :parameters (?a - aircraft
    ?c1 ?c2 - city)
  :duration
    (= ?duration (/ (distance ?c1 ?c2)
      (fast-speed ?a)))
  :condition
    (and (at start (at ?a ?c1))
      (at start (>= (fuel ?a)
        (* (distance ?c1 ?c2) (fast-burn ?a))))))
  :effect
    (and (at start (not (at ?a ?c1)))
      (at end (at ?a ?c2))
      (at end (increase total-fuel-used
        (* (distance ?c1 ?c2) (fast-burn ?a))))))
    (at end (decrease (fuel ?a)
      (distance ?c1 ?c2) (fast-burn ?a))))))
```



Proble Description

```
define (problem zeno-travel-1)
  (:domain zeno-travel)
  (:objects plane - aircraft ernie scott dan - person
            city-a city-b city-c city-d city)
  (:init
   (= total-fuel-used 0) (= debarking-time 20) (= boarding-time 30)
   (= (distance city-a city-b) 600) (= (distance city-b city-a) 600)
   (= (distance city-b city-c) 800) (= (distance city-c city-b) 800)
   (= (distance city-a city-c) 1000) (= (distance city-c city-a) 1000)
   (= (distance city-c city-d) 1000) (= (distance city-d city-c) 1000)
   (= (fast-speed plane) (/ 600 60)) (= (slow-speed plane) (/ 400 60))
   (= (fuel plane) 750) (= (capacity plane) 750)
   (= (fast-burn plane) (/ 1 2)) (= (slow-burn plane) (/ 1 3))
   (= (refuel-rate plane) (/ 750 60))
   (at plane city-a) (at scott city-a) (at dan city-a) (at ernie city-c))
  (:goal (and (at dan city-a) (at ernie city-d) (at scott city-d)))
  (:metric minimize total-time))
```



PDDL 2.2: Being Conservative

- **Consolidate existing techniques** for PDDL2.1, so that planners can catch up
- **Understand results** in IPC-3 by making sense of data
- **Handle existing features**, in particular complex optimization criteria
- **Widen applicability focus**



PDDL Extensions

- **Axioms:** derived predicates

(:derived (above ?x ?y)

(or (on ?x ?y)

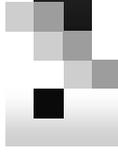
(exists (?z) (and (above ?x ?z)

(above ?z ?y))))))



PDDL Extensions

- ***Timed initial facts:*** propositions that occur independently of actions taken by planner
 - (at 9 (open shop))
 - (at 17 (close shop))



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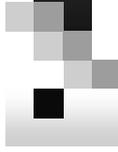
(Sub)optimal Planning

- **Hardness** [Helmert] Optimisation in many domains much harder than satisfiability
- **Special prices** for optimal planners or ones that give performance guarantees
- Comparison with existing **special-purpose** optimal **solvers**
- ...



Effort of Hand-Coding

- Measuring ***coding time*** invested for adding control knowledge
- Measure (compressed) ***ASCII text length***
- Let ***users other than the programmers*** generate the knowledge
- ...



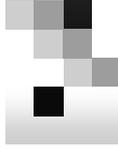
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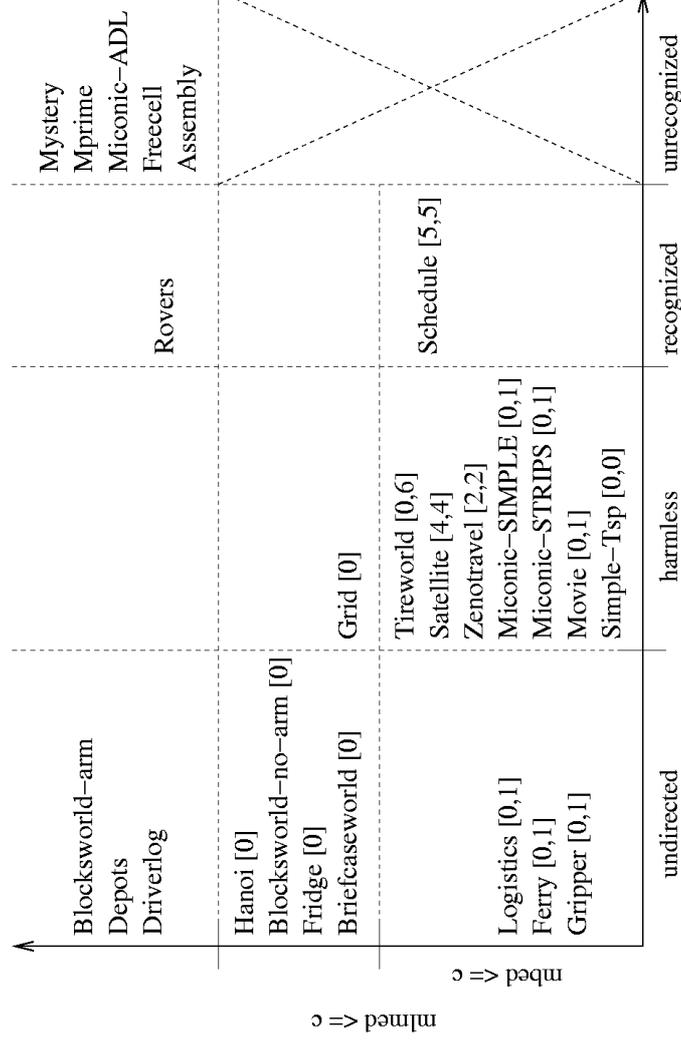


Benchmarks...

- ...have an important impact on the field
- ...are more and more taken from the IPC collections
- ...should:
 - be realistic
 - cover diverse problem structures



Problem Structure – wrp to h^+



„Heuristic planners are fast.“ --- „Across certain classes of domains!“



Problem Structure, ctd.

- The benchmarks ought to cover the „range of interesting problem structures“
 - ... in particular, they shouldn't all have the same structure
- How to measure „structure“?
 - Intuitively: Logistics \neq Blocksworld
 - Wrpto h^+
 - Wrpto computational complexity



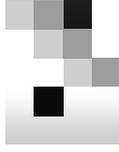
Realistic...

- ...is a word with two meanings:
 1. *„not restricted to a too simplified model“*
 2. *„close to applications“*
- 1. is a prerequisite of 2.
- IPC-3 made great progress on 1., as well as some steps towards 2.
- There is more to be done on 2.



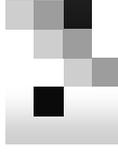
Close to Applications

- Airport ground traffic control [Hoffmann et al.]
- Biological Pathway Discovery? [Khan et al.]
- Miconic (fully fledged) [Koehler]
- Pipesworld [Milidiu et al.]
- Promela Verification [Edelkamp]
- PSR [Thiebaut]
- Space applications [NASA]
- Pressure networks [Kurien]



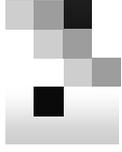
IPC-4 Benchmarks

- How to combine „close to applications“ and „cover broad range of structures“?
 - With application-oriented domains that cover a broad range of structures...
 - Maybe: one group for very application-oriented domains (eg. Miconic, Pipes, PSR,...), another group for structurally very characteristic domains (eg. Blocks, Log, Mystery, n^2-1 puzzle, Sokoban, Settlers,...)



Overview

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- **Organisation**
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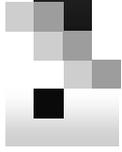
Infrastructure

- Test Domains: Blocks + Derived, ZenoTravel
+ Timed-Initial Facts (compiled and explicit)
- Validator VAL: PDDL 2.1 -> PDDL 2.2
[Durham]
- Converter: ADL -> STRIPS [Hoffmann]
- Grounder: PDDL2.2 -> Grounded PDDL 2.2
[Edelkamp]



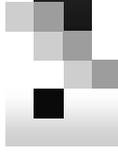
Time Table

- Now: Language extensions fixed (PDDL 2.2), first testing examples out
- 01/04: registration deadline for planners
- 02/04 – 03/04: data collection
- 05/04: data evaluation
- 06/04: detailed results presentation at ICAPS'04
- Summer 05: competitors publication



IPC-4 at ICAPS'04

- Detailed results presentation:
 - extra room throughout conference, maybe after award ceremony
 - in form of posters, assisted with (visualisation, eg.) tools
- Competitors handout:
 - extended abstracts describing all the competitors, distributed to ICAPS participants



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Summary

- There will be classical and probabilistic (and non-deterministic?) parts of IPC-4
- The ingredients for the classical part are:
 - Moderate PDDL extensions
 - Careful choice of benchmark domains
 - Separate prize(s) for best *optimal* planner(s)
 - Detailed information available online



CFP

- A competition without competitors is boring
- There will be terrific prizes
- We explicitly invite the optimal approaches to come back to us
- ...everybody else can come, too

Mips

Yepa-Server (Plan To Gantt Chart Converter) - info

Welcome to YEPa - Visualization Environment for Plans
Please enter the following

Input requirements

- Text planner
- Text domain
- Text problem
- Text options

Planner Executable file-name
Domain file-name
Problem file-name
Options to the planner (separated by space)

Tools

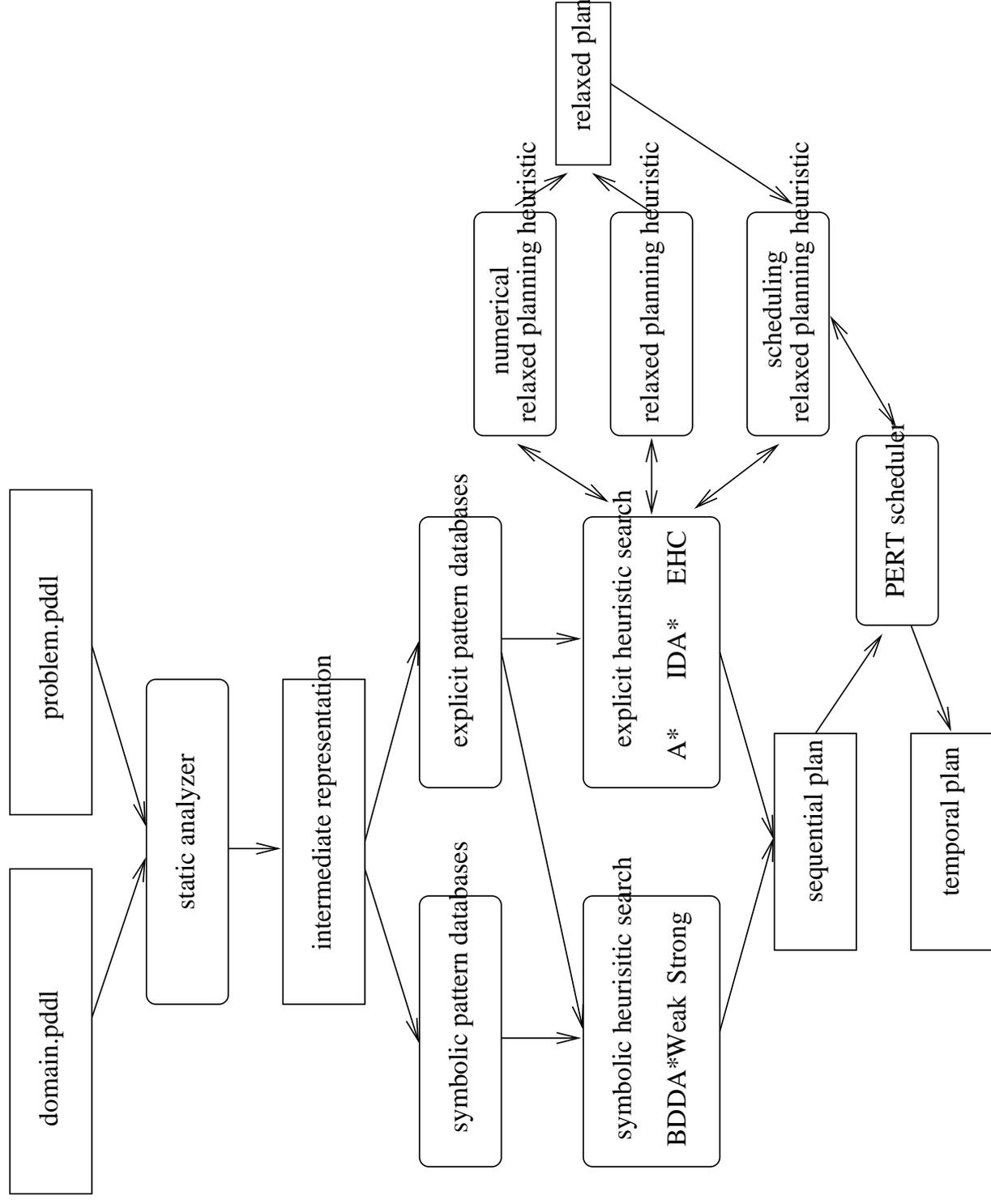
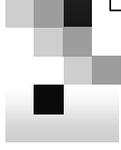
Object browser

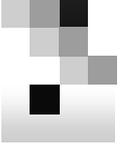
Text object: domain
/home/edekamp/comp/naip5/

Text object: problem
/home/edekamp/results/Test1/ZenoTravel/Time/pfile9

(5,494, 28, 379) Step 1 (1)

International Planning Competition International Planning Competition





25/09/2003

International Planning Competition
International Planning Competition